**University of Central Missouri**

**Department of Computer Science & Cybersecurity**

**CS5720 Neural Networks and Deep Learning**

**Summer 2025**

**Home Assignment 2. (Cover Ch 4,5)**

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**Submission Requirements:**

* Total Points: 100
* Once finished your assignment push your source code to your repo (GitHub) and explain the work through the ReadMe file properly. Make sure you add your student info in the ReadMe file.
* Submit your GitHub link and video on BrightSpace.
* Comment your code appropriately ***IMPORTANT.***
* Make a simple video about 2 to 3 minutes which includes demonstration of your home assignment and explanation of code snippets.
* Any submission after provided deadline is considered as a late submission.

**Question 1: Cloud Computing for Deep Learning (20 points)**

Cloud computing offers significant advantages for deep learning applications.

(a) Define **elasticity** and **scalability** in the context of cloud computing for deep learning. (10 points)  
(b) Compare **AWS SageMaker**, **Google Vertex AI**, and **Microsoft Azure Machine Learning Studio** in terms of their deep learning capabilities. (10 points)

**Expected Output**

Write the definition and comparison for (a) and (b). No code needed.

**Question 2: Convolution Operations with Different Parameters (20 points)**

**Task: Implement Convolution with Different Stride and Padding (10 points)**

Write a Python script using **NumPy and TensorFlow/Keras** to perform **convolution** on a **5×5 input matrix** using a **3×3 kernel** with varying parameters.

1. Define the following **5×5 input matrix**:

A number with black text

AI-generated content may be incorrect.

1. Define the following **3×3 kernel**:

A number lines with numbers

AI-generated content may be incorrect.

1. Perform **convolution operations** with:
   * **Stride = 1, Padding = ‘VALID’**
   * **Stride = 1, Padding = ‘SAME’**
   * **Stride = 2, Padding = ‘VALID’**
   * **Stride = 2, Padding = ‘SAME’**
2. Print the **output feature maps** for each case.

**Expected Output**

Print the output feature maps for

* + **Stride = 1, Padding = ‘VALID’**
  + **Stride = 1, Padding = ‘SAME’**
  + **Stride = 2, Padding = ‘VALID’**
  + **Stride = 2, Padding = ‘SAME’**

**Question 3: CNN Feature Extraction with Filters and Pooling (30 points)**

**Task 1: Implement Edge Detection Using Convolution (15 points)**

Write a Python script using **NumPy and OpenCV (cv2)** to apply **edge detection** on an image using a **Sobel filter**.

* Load a grayscale image (you can use any sample image).
* Apply the **Sobel filter** for **edge detection** in the **x-direction** and **y-direction**.
* Display the original image and the filtered images.

Use the following Sobel filters:

A diagram of a mathematical equation

AI-generated content may be incorrect.

**Task 2: Implement Max Pooling and Average Pooling (15 points)**

Write a Python script using **TensorFlow/Keras** to demonstrate **Max Pooling** and **Average Pooling**.

* Create a **random 4x4 matrix** as an input image.
* Apply a **2x2 Max Pooling** operation.
* Apply a **2x2 Average Pooling** operation.
* Print the original matrix, max-pooled matrix, and average-pooled matrix.

**Expected Output**

**Task1: Edge Detection using Sobel Filter**

* Display **three images**:
  1. **Original Image**
  2. **Edge detection using Sobel-X**
  3. **Edge detection using Sobel-Y**

**Task2: Pooling Operations on Random 4×4 Matrix**

* Printed **original matrix, max pooled matrix, and average pooled matrix**.

**Question 4: Implementing and Comparing CNN Architectures (30 points)**

**Task 1: Implement AlexNet Architecture (15 points)**

Write a **Python script** using **TensorFlow/Keras** to implement a simplified **AlexNet** model with the following layers:

* **Conv2D Layer**: 96 filters, kernel size = (11,11), stride = 4, activation = ReLU
* **MaxPooling Layer**: pool size = (3,3), stride = 2
* **Conv2D Layer**: 256 filters, kernel size = (5,5), activation = ReLU
* **MaxPooling Layer**: pool size = (3,3), stride = 2
* **Conv2D Layer**: 384 filters, kernel size = (3,3), activation = ReLU
* **Conv2D Layer**: 384 filters, kernel size = (3,3), activation = ReLU
* **Conv2D Layer**: 256 filters, kernel size = (3,3), activation = ReLU
* **MaxPooling Layer**: pool size = (3,3), stride = 2
* **Flatten Layer**
* **Fully Connected (Dense) Layer**: 4096 neurons, activation = ReLU
* **Dropout Layer**: 50%
* **Fully Connected (Dense) Layer**: 4096 neurons, activation = ReLU
* **Dropout Layer**: 50%
* **Output Layer**: 10 neurons, activation = Softmax

Print the **model summary** after defining it.

**Task 2: Implement a Residual Block and ResNet (15 points)**

Write a Python script to define a **Residual Block** and use it to build a simple **ResNet-like model**.

1. Implement a function residual\_block(input\_tensor, filters) that:
   * Takes an **input tensor**.
   * Applies **two Conv2D layers** (each with 64 filters, kernel size = (3,3), activation = ReLU).
   * Includes a **skip connection** that adds the input tensor to the output before activation.
2. Create a **ResNet model** that:
   * Uses an **initial Conv2D layer** (64 filters, kernel size = (7,7), stride = 2).
   * Applies **two residual blocks**.
   * Ends with a **Flatten layer, Dense layer (128 neurons), and Output layer (Softmax)**.

Print the **model summary** after defining it.

**Expected Output**

The output should display:

1. The **model summary** for **AlexNet**.
2. The **model summary** for the **ResNet-like model**.